Eddy-Current Signal Processing Applied to Aircraft Fuel Tubes Maintenance

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Air Transat Flight TSC 236

→ August 24th, 2001, evening.
 → North Atlantic Ocean, Azores Islands.
 → FL 350, Airbus A330-243.
 → FR Toronto (YYZ) TO Lisbon (ZYD).



Air Transat Flight TSC 236

Actually FR Toronto TO Azores...



Airbus A330 - Engine Number 2

Intriguing oil parameters: - Low oil temperature. - High oil pressure. - Low volume in the oil reservoir.



	ENGINE Nr 1	Engine Nr 2
OIL TEMPERATURE	110ºC	65ºC
OIL PRESSURE	80 psi	150 psi
OIL QUANTITY	17 liters	14 liters

Rolls Royce RB 211 Trent 772B



Airbus A330 Engines

 Normal engines parameters, but...
 Inexplicable low FOB (Fuel on Board) quantity readings.



E / WD Screen

In addition, the following message illuminate in the E / WD (Engine Warning Display):

T TK XFRD

Which means: "Trim Tank Empty"



The Azores Glider

At 06:13 pm of that day the engine number 2 flamed out. \rightarrow 13 minutes later, the left engine flamed out too. With no fuel, 65 nautical miles away from Lajes Airport, Terceira Island, Azores and at 34,500 ft altitude, the ~ 160 tons aircraft became an air transat immense glider.

Lajes Airport Approach



Azores Glider Landing

 Despite small fires in the landing gear and minor structural damage, the emergency landing was ok at RWY 33.
 However, eighteen people suffered injuries during the emergency evacuation.





Accident Investigation

Investigators found that the strange parameters of engine Nr 2 were caused

by a fuel leak through a crack in the fuel line FUEL downstream of the fuel-oil heat exchanger.

OIL	ENGINE Nr 1	ENGINE Nr 2
TEMP.	110ºC	65ºC
PRESS.	80 psi	150 psi
VOLUME	17 liters	14 liters

Accident Investigation

The fuel leak rate reached 13 ton/h.
That's the reason why the aircraft got no fuel.



Accident Investigation

The crack was a result of a hard contact between fuel and oil lines due to a non appropriate routine maintenance dozens of flight-hours before.



Why an aircraft get no fuel?

In the aviation history, a lot of accidents have been occurred due to lack of fuel. The main reasons commonly are: - wrong flight range calculations - fuel indicators malfunction. - bad weather conditions. - hard air traffic. - navigation errors, etc...

Non Destructive Testing

The rupture of a fuel tube is a quite rare reason for lack fuel because the tubes are properly inspected. The aircraft tubing is inspected through several Non Destructive **Testing methods:** - Liquid Penetrant; - Ultra Sound; - X-Ray; - Eddy-Current.

Eddy-Current Testing

The Eddy-Current Testing (ECT) is an electromagnetic method widely used in aircraft inspection. The defects identified through ECT allows important inspection decisions and guarantees the aircrafts safe operations.



Eddy-Current Testing (ECT) The ECT is based on the introduction of an alternate current bobbin coil probe in the fuel tube. A primary magnetic field is generated.



Eddy-Current Testing (ECT)

 The primary magnetic field induces circular Eddy Currents in the fuel tube which generates a secondary magnetic field opposite to the primary field.
 The electric circuit have resistive (R) and inductive (XL) components.





Eddy-Current Testing (ECT) By using the complex plan to represent the resistance R and the inductive reactance X_L , the impedance of the circuit is represented by a vector which length is Z.

 $\rightarrow \alpha$ is the Phase Angle.

 $Z = \sqrt{R^2 + X_L^2}$

Eddy-Current Testing (ECT) When the probe passes through a defect, the impedance forms an "8" shaped Lissajous figure.





Eddy-Current Testing (ECT) One of the most important signal characterists is the Phase Angle C formed by a (Volts) horizontal line α and the straight 2 0 line common to -2 the two petals of -4 the Lissajous figure, clockwise -2 -6 Volts measured.

Defect Depth and Localization

The Phase Angle determines the depth of the defect and if it is internal or external to the fuel tube by using the Calibration Curve. DEFECT Depth (%)TUBE 80 EXTERNAL WALL (Volts) 60 40 **CALIBRATION CURVE** 20 20 80 100 120 160 40 60 140180 Phase Angle α (°)









Eddy Current Material Noise This noise is originated in the variations of magnetic properties of fuel tube material. **IMPEDANCE** It produces 5 Volts distortions in the Lissajous figures to such an extension 0 that Phase Angle reading is simply -3 impossible at all. 0 Volts

5

Data Acquisition Noise

 → The instrumentation noise produces a blurry Lissajous figure which can jeopardize Phase Angle determination.
 → The Wavelet Transform methodology is used for the removal of this noise.







The Wavelet Transform (WT)

→ WT is a time-scale signal transformation which combines the use of variable time and scale windows.
→ When lower frequency information is needed, large time intervals are used and vice versa.

Scale

Time

Amplitude

The Wavelet Transform (WT)

The Wavelet Transform is very sensitive to discontinuities in time domain, which is typical of Eddy Current signals. It is a method where the transformed time-frequency domain can be varied, allowing for a more detailed description of the time-frequency behavior of the signal being analyzed.

The Wavelet Transform (WT)

Through the Matlab tool, the signal can be decomposed and analysed in how many separate frequency **bands** are needed.

Resistance Original Signal Decomposition



The Wavelet Transform (WT) \rightarrow For a given Eddy-Current signal s(x), the WT is the convolution of s(x) with a set of Wavelet functions $\Psi_{a,b}(x)$ resulting in a set of coefficients $C_{a,b}$:

$$C_{(a,b)} = \int_{-\infty}^{+\infty} \mathbf{s}(x) \psi_{a,b}(x) dx$$

A Wavelet function $\psi_{a,b}(x)$ has two characteristic parameters: the scale "a" and the position "b" which change continually.

The Wavelet Function $\psi_{a,b}(x)$

The characteristic parameters:

Scale "a"



Position "b"



 $C_{(a,b)}$ $= \int \mathbf{s}(\mathbf{x}) \psi_{a,b}(\mathbf{x}) d\mathbf{x}$

The Wavelet Function $\psi_{a,b}(x)$ \Rightarrow A complete set of basic Wavelet functions $\psi_{a,b}(x)$ can be obtained by the dilation and shifting of $\psi(x)$ according to:

$$\Psi_{a,b}(x) = \frac{1}{\sqrt{|a|}} \Psi\left(\frac{x-b}{a}\right)$$

where $(a,b) \in \mathbb{R}$ and $a \neq 0$. $C_{(a,b)} = \int_{-\infty}^{+\infty} s(x) \psi_{a,b}(x) dx$

The Wavelet Function $\psi_{a,b}(x)$ > If one multiplies each coefficient by the properly dilated and shifted Wavelet function, one should regenerate the original function s(x).

The Wavelet Function $\psi_{a,b}(x)$ There exists a relationship between the Wavelet scale and the frequency. A small scale will produces compressed Wavelet where the details changes rapidly in higher frequencies. With a large scale, the Wavelet is expanded and details change slowly with lower frequencies.

De-noising Methodology

Eddy-Current signals de-noising is performed by transforming the data to the time frequency domain using multiple scale levels by a Wavelet transform. \rightarrow A given signal s(x) is decomposed in each scale level into an "approximation" component A; and a "detail" component D_i .

De-noising Methodology

Example: 3 level decomposition tree of a signal s into approximations and details.



s = A3+D3+D2+D1=A2+D2+D1=A1+D1

Applying the Methodology

→ The first step is to separate the inductive component (X_L) and the resistive component (R) of the noisy Eddy Current signal:





Frequency Decomposition

Then, X_L and R are multi level frequency decomposed through WT:









Wavelet C(a,b) Coef. Selection Frequencies removal:





-1 -1.5

-2

-1 Volts

4.5

Signal Recomposition

After noise removal, the de-noised reactance and resistance components are recomposed producing a clean Lissajous figure from which the Phase Angle can be extracted.









Probe Wobble Noise

This noise is generated by the necessary slack PROBE between the probe and the fuel tube. The greather the radial movement of the probe, the greather the inductive component variation of the Eddy

Current signal.



Probe Wobble Noise

Due to this noise, the Lissajous figure changes as well as its Phase Angle α . Consequently, this noise hinders the signal analysis and reduces inspection reliability. $\alpha 1=135^{\circ} \rightarrow 32\%$ depth IMPEDANCE Volts $\alpha 2: 120^{\circ} \rightarrow 43\% \text{ depth}$ Depth (%) 08 40 2 EXTERNAL WAL -2 -4 -6 Volts

CALIBRATION CURVE

60

80

40

20

20

100 120 140 160

180

Probe Wobble De-Noising

<u>Example: X, component, Ø19.05mm</u> fuel tube with 2 artificial holes.

The signal was generated by a MIZ-17ET equipment.





Probe Wobble De-Noising

Four wavelet functions were used for

de-noising:



→ An 8 level frequency decomposition allowed a convenient selection of the approximation (A_i) and the detail (D_i) components.

De-Noising – Haar wavelet



 $\Psi_{(x)}$

0.5

-0.5

0.2 0.4 0.5 HAAR



De-Noising – Symlet wavelet No probe wobble; different X_L



SYMLET







De-Noising – Daubechies wavelet



The denoising of Eddy Current signals is a process which determines the better $\Psi_{(x)}$ Wavelet function $\psi_{a,b}(x)$: -> ... and the adequate set of coefficients Ca.b, whith the characteristic parameters "a" scale and "b" position.





→ Besides that, the noisy signal s must be decomposed in each scale level into an "approximation" component A_i and a "detail" component D_i .

The data acquisition instrumentation noise, although it may distorts a lot the signal, it is not difficult to be removed as it is a high frequency noise.



 The material noise is originated in the magnetic properties variations caused for example by the manufacturing process of the tube.
 The Eddy Current Lissajous figure is completely distorted by this noise.







The probe wobble signal de-noising offers reliable results as it allows an efficient removal of noise, maintaining the essential signal information. The methodology above described is being applied in inspection automation of fuel tubes by using a Matlab software enhanced by artificial inteligence.