

The background features a collage of research papers and charts. On the left, a line graph shows 'Relative value' on the y-axis (0% to 100%) and 'Increase in Reach Extent (cm)' on the x-axis (-8 to 14). A line starts at approximately 40% and rises to 100%. Another chart shows a line starting at 0 and rising to 14. Text from the papers is partially visible, including 'Figure 2. Comparison of...', 'from Mirror Im...', 'hilitation and Med...', 'improved reach ext...', 'icant difference bet...', 'Reinkensmeyer DJ.', 'upper extremity in c...', 'Guide results. Proceed...', 'hilitation Robotics; 2...', '(Korea); Human-Frien...', 'Research Center; 2003; p...', 'Base Plat', and '0'.

## Error Augmentation as a Possible Technique for Improving Upper Extremity Motor Performance after a Stroke - a pilot study

Eli Carmeli\*, Sharon Israely, Sara Rosenblum

\*Physical Therapy Department,  
University of Haifa, Israel



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Brain Disorders and Therapeutics  
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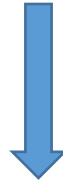
A stack of papers is visible in the top-left corner, with a prominent red tab. The papers appear to be medical or scientific documents, with some text and a graph visible. The red tab is positioned over the top of the stack and contains the word 'Background' in white text.

# Background

- **In the United Kingdom, strokes affect 150,000 people each year.**
- **Only 33% to 70% of patients recover useful arm function (Huang & Krakauer 2009).**
- **Conventional neuro-rehabilitation seems to have little impact on the impairment beyond the spontaneous biological recovery.**
- **Neuro-rehabilitation is mainly improve motor control of proximal segment and lower limb, with some improvement of the proximal segment of upper limb (Kordelaar J et al 2013).**

# Background

**Kinematic impairments of *reaching movements* are related to abnormal reaching performance in post-stroke subjects.**



**increased in movement duration**

**decreased velocity**

**increased variability in path trajectory**



**leading to restricted use or even non-use of the affected hand.**

# New treatment approach

- Error Augmentation, instead of neuro facilitation, is proposed as a possible Technique for Improving Upper Extremity Motor Performance.
- This system uses the error enhancement method, in which movement errors are temporarily magnified to encourage learning.



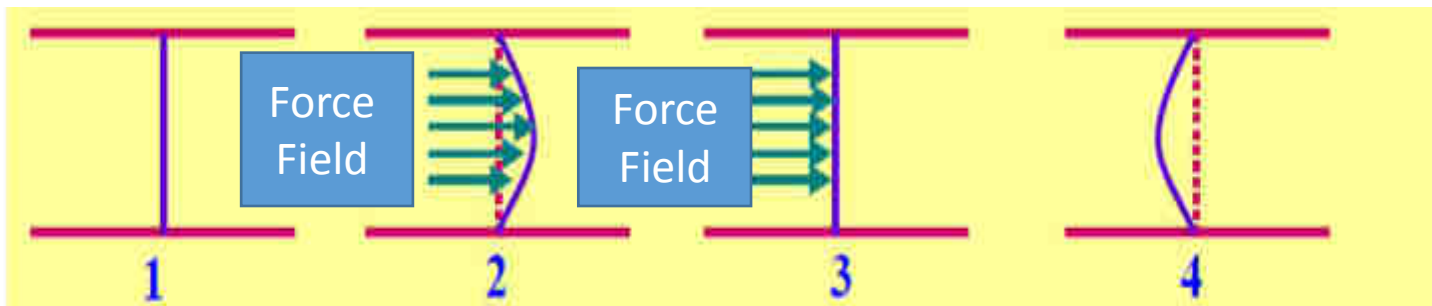
The background features a stack of papers on the left side, with a prominent red rectangular box containing the title 'Background' in white text. The papers behind the box show some technical data, including a vertical axis labeled 'Relative value' with percentages like 100%, 80%, 60%, and 40%.

# Background

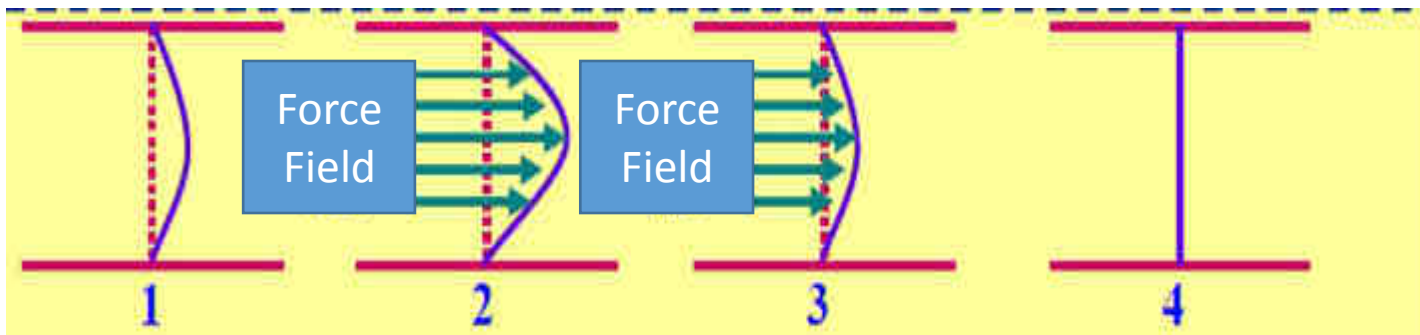
- **Error augmentation (EA) utilizes erroneous sensory feedback (e.g., tactile/vision) to enhance motor recovery after neurological damage.**
- **The computer singles out the patient's hand movement, every moment, from a specific desired trajectory, thus it provides a proportional sensory feedback (i.e., incorrect, mistaken, amplified, and exaggerated) to magnify the errors in proportional manner.**
- **The presence of this error in the haptic systems, forces patients to strengthen their control as they counteract the error-driven disturbance to the movements.**

# Why adaptation leads to learning?

A. Effect of error augmentation on correct movement trajectory- adaptation



B. Effect of error augmentation on erroneous movement trajectory



A stack of papers is visible in the top-left corner, with a red tab labeled "Rational" in white text. The papers behind the tab show a graph with a y-axis labeled "Relative value" and percentages (100%, 80%, 60%, 40%) and some text.

# Rational

- **Motor learning is based on “making movement errors during practice”.**
- **Therefore, manipulation of error signals during practice is believed to be central to movement adaptation.**
- **Intrinsic feedback mechanisms are often impaired, providing augmented feedback by making errors are more noticeable to the senses.**
- **Larger errors increase motivation to learn.**
- **Machine-assisted training is precise; sustained for long time; measure progress automatically; and produce a wide, monitored range of forces and motions.**



## Principles during 'error augmentation' therapy

1. Many repetitions.
2. High intensities.
3. Variability of practice
4. Advanced practice

*Bowden et. al. 2013, Krakauer 2005*



A stack of papers is visible in the top-left corner. The top paper shows a graph with a y-axis labeled 'Relative value' and percentages (100%, 80%, 60%, 40%). A yellow sticky note is attached to the top of the stack.

# Research question

**Can error enhancement of the  
velocity component improve  
motor performance  
and  
functional abilities?**

A stack of papers is visible in the top-left corner, with a yellow sticky note placed on top of them. The sticky note contains the text 'Research/Pilot study aims'.

## Research/Pilot study aims

### **Primary**

to measure the effect of error augmented therapy.

### **Secondary**

to compare outcomes between sEMG results and Fugel Myere score.

to evaluate association between writing skill and arm reach.



# Participants

**Stroke (n =5), males**

**Control (n =5) age-and-gender matched**

**Inclusion criteria: basic understanding, partial UE active movement, ability to open/close fingers 5 times.**

**Exclusion criteria: apraxia, agnosia, spasticity, shoulder subluxation /pain of UE.**

# Outcome measure (1)

## Digital plate + software

1. Writing speed
2. Pressure
3. Off-time
4. On-time to- off-time time ratio

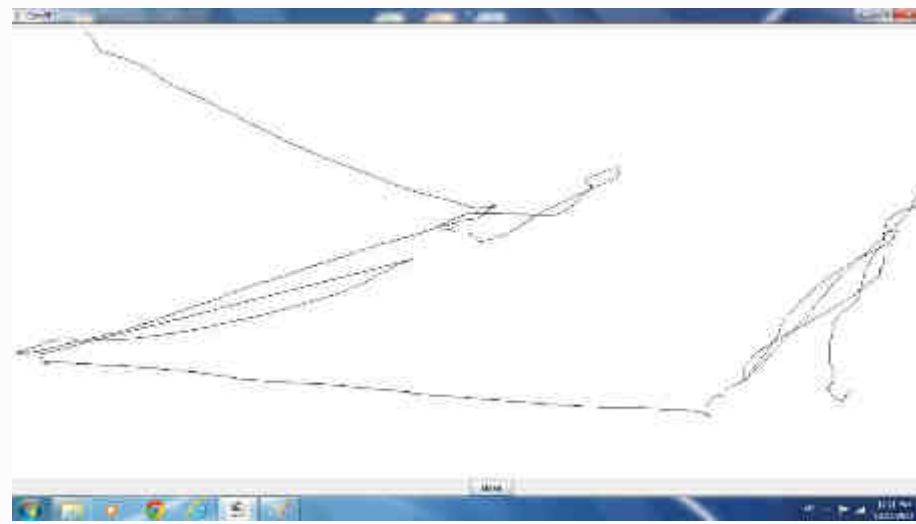
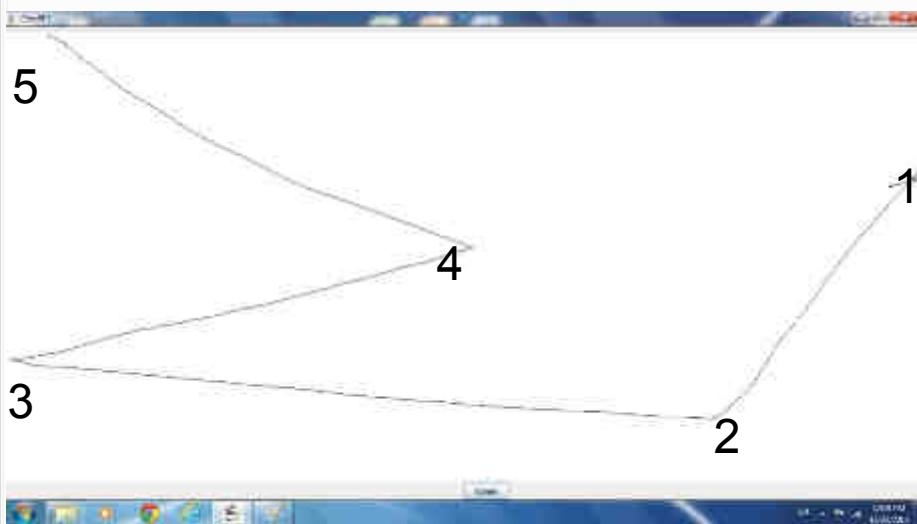
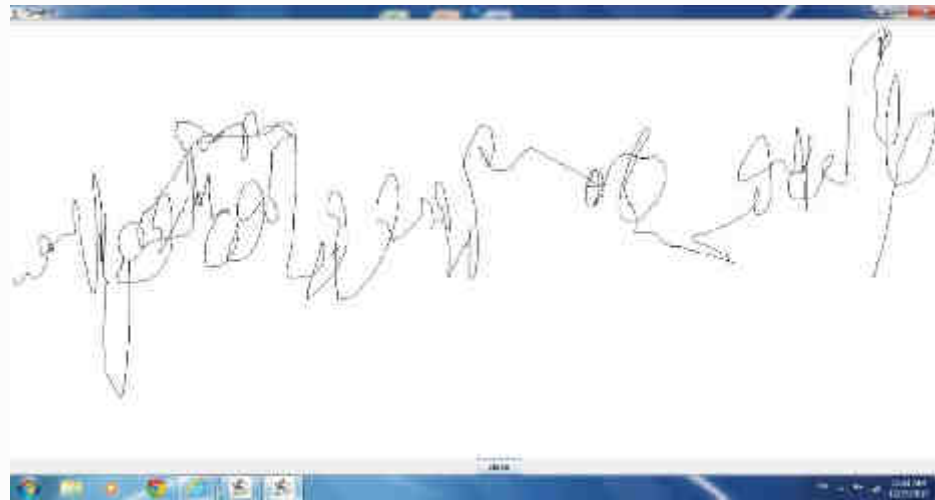
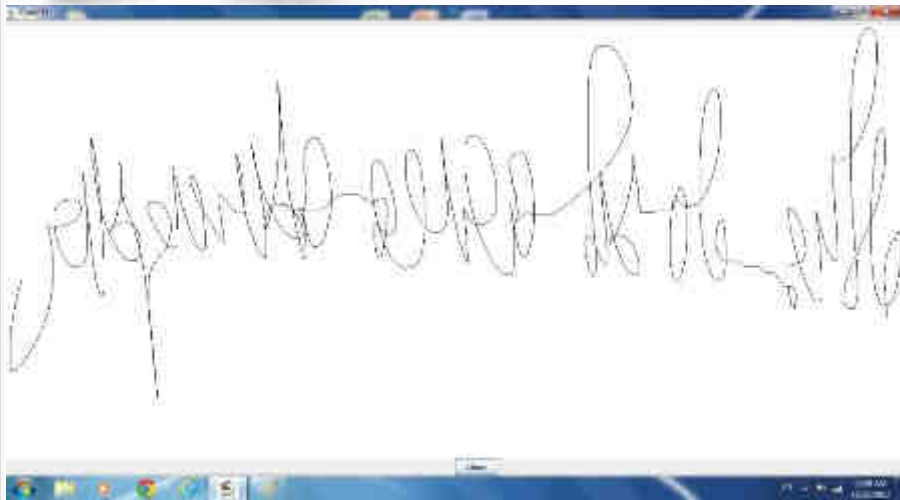
(Rosenblum S et al., 2013)



# Decoding writing and connecting dots in healthy individuals compared to stroke patients using ComPET

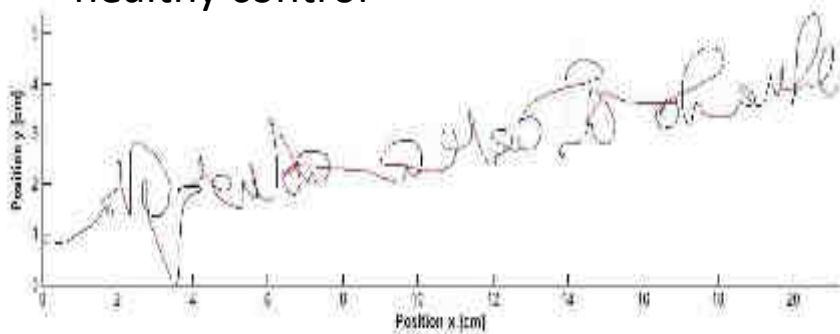
Healthy control

Stroke



# Decoding writing and connecting dots

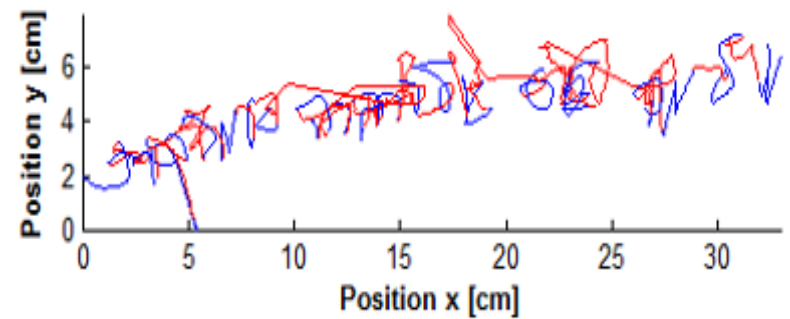
**A:** “characteristics **on/off-time**” - healthy control



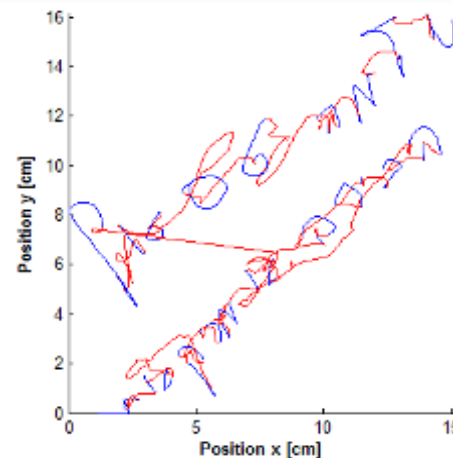
The **red lines** represent the course of pen movements during their stay in the air (off-time).

**A1.** Stroke patient has vague movements, jerky rather than smooth in compare to **A2**

**B1.** Pre treatment: “characteristics **on/off-time**” - Stroke



**B2.** Post-treatment: “characteristics **on/off-time**” - Stroke



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## Fugl Meyer (2)

Motor assessment of the upper extremity

Consists of 33 items.

A 3-point scale:

0 - inability to complete the test item

1 - partial ability


2 - full completion

Assessing DTR

Movement synergy

Movement isolation

Grasping

A stack of papers is visible in the top-left corner, partially obscured by a blue banner. The banner contains the title 'FM- Validity & Reliability' in bold black text.

# **FM- Validity & Reliability**

**Construct validity (spearman`s rho):**

**Vs. Box and Blocks test 0.921**

**Vs. Action Research Arm Test 0.925**

**ICC inter-rater 0.99**

**ICC intra-rater 0.95**

**Standard Error Measurement (SEM) 3.6 points**

**Smallest Real Difference (SRD) 5.2 points**

**Minimal Clinically Important Difference 10 points**



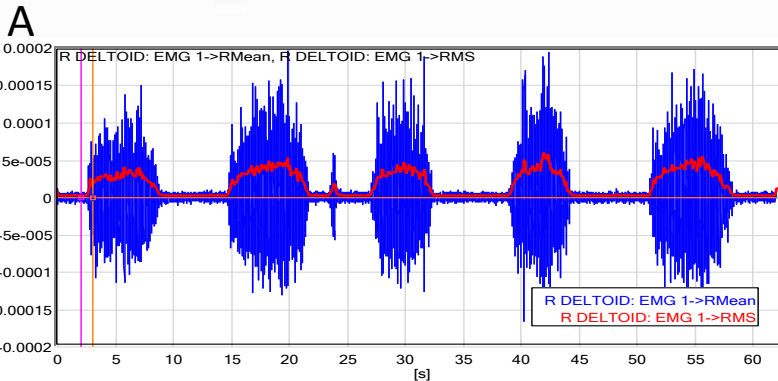
# Outcome measure (3)

- sEMG, wireless system, Trigno Lab, Delsys, USA
1. Muscle amplitude analysis (%MIVC\*)
  2. Muscle onset
  3. Co-activation Index



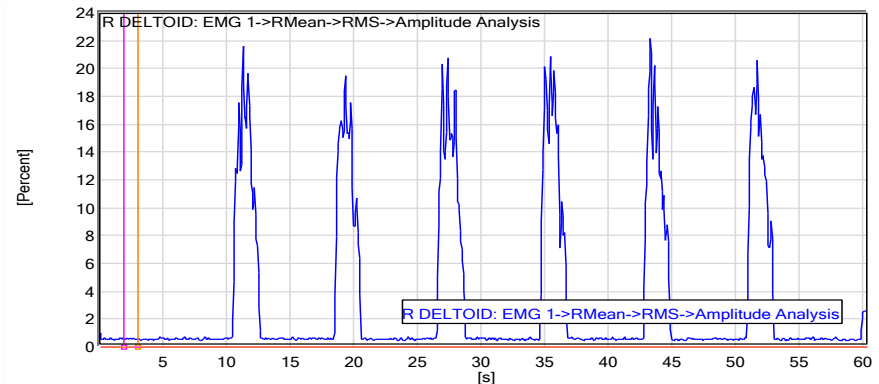
\*MIVC – **M**aximum **I**sometric **V**oluntary **C**ontraction

# Data analysis - sEMG



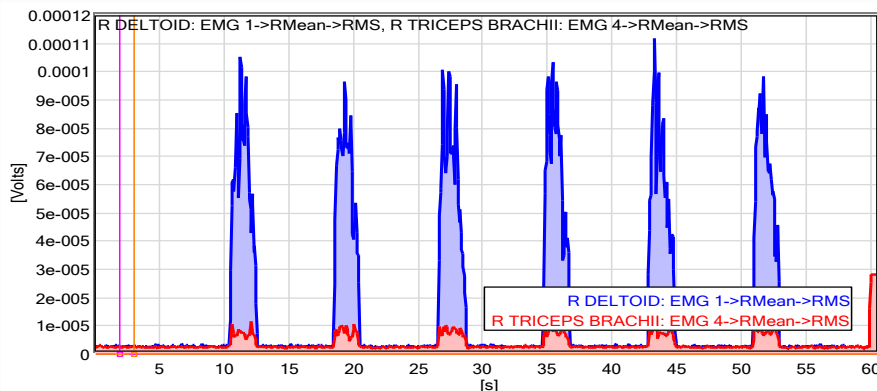
A. **Blue:** Raw EMG signal with positive and negative values **Red:** EMG signal after processing of Root Mean Square (RMS). Combining Rectification processing (transfer of all negative values to positive values) and signal smoothing by Filtration Unites are in Voltage as a result of an 'action potential'.

B



B. How much (in %) of the maximum isometric contraction the patient Deltoid uses during the forward reach.

C



C. **Root Mean Square (RMS):**

Deltoid (**blue**) vs. Triceps (**red**).

Deltoid is the **prime mover** during forward reach.

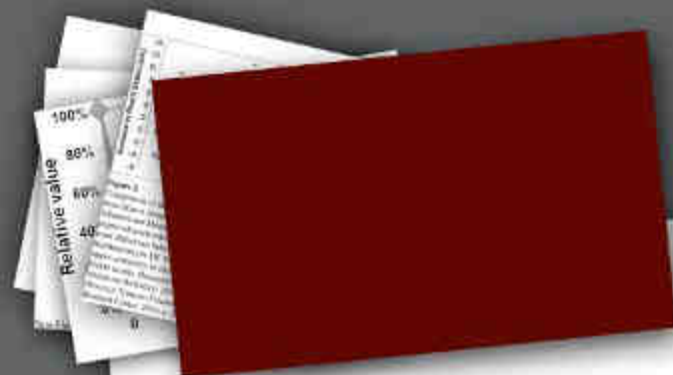
**Index Co-activation** measure through data on the subjects muscles activity relative to Deltoid activity.

# Outcome measure (4) and Intervention - 4 weeks/3Wk

Robotic system, ROBOTTEACHER-2, Bioxtreme, ISRAEL

Average error (in cm).  
Total score (points).





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# A preliminary investigation of error enhancement of the velocity component in stroke patients' reaching movements

*Ronit Givon-Mayo, Esther Simons, Avi Ohry, Hana Karpin, Sharon Israely, Eli Carmeli*

International Journal of Therapy and Rehabilitation, April 2014, Vol 21, No 4

# Results

|               | Study Group | Control Group |
|---------------|-------------|---------------|
| Gender (Male) | 5           | 5             |
| Age (Years)   | 57.2 ±8.2   | 54.8 ±7.8     |



# Pilot study – preliminary results

|                                 | <b>Study group (N =5)</b> |             | <b>Control (N =5)</b> |             |
|---------------------------------|---------------------------|-------------|-----------------------|-------------|
|                                 | <u>Pre</u>                | <u>Post</u> | <u>Pre</u>            | <u>Post</u> |
| Fugel-Meyer (points)            | 36.4                      | 44.2*       | 51.8                  | 55.7*       |
| Total “accuracy” score (points) | 2328                      | 2802*       | 2960                  | 3574*       |
| Average error (cm)              | 6.2                       | 3.7*        | 2.3                   | 0.6*        |

Data robotic system - the degree of improvement (in points)

\*( $P > 0.05$ ) Independent sample t-test

# Velocity profile of 2 representative patients after stroke

Stroke  
With error augmentation

Stroke ("Control")  
Without error augmentation

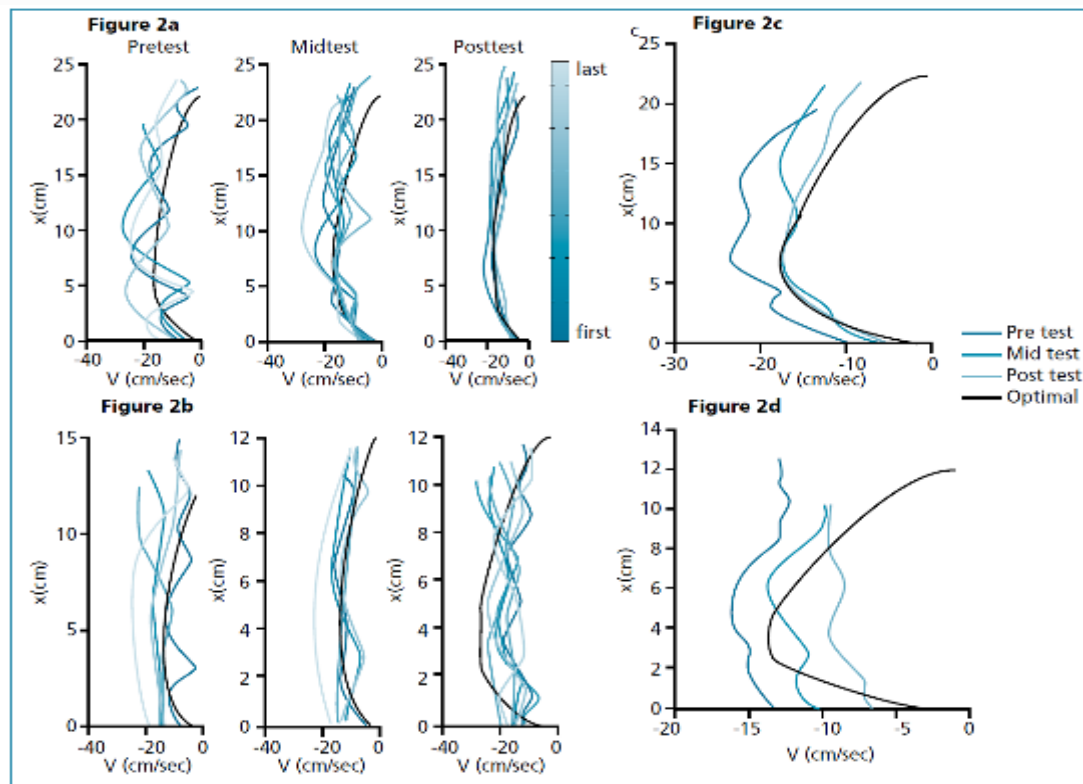
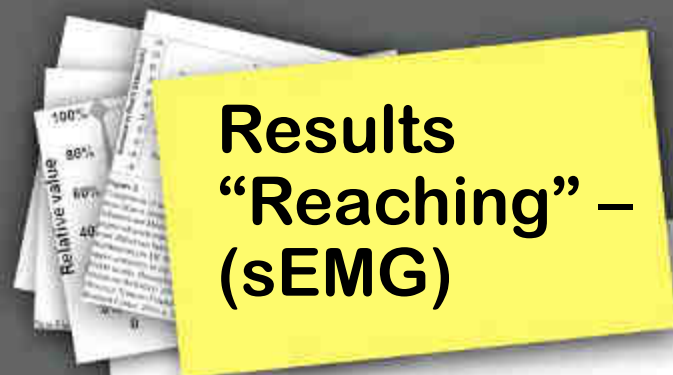


Figure 2. Movement velocity profiles for a representative experimental subject: (a) and a representative control subject: (b) at three time points (pre, mid and post test), compared with the optimal velocity profile (black line). The successive profiles are represented by graduated colors ranging from cyan (first profiles) to magenta (last profiles); (c) The average velocity profile for the experimental subject; and (d) the control subject, compared with the optimal velocity profile (black line).

Givon-Mayo et. al.  
(2014)



## **Results “Reaching” – (sEMG)**

- 1. Stroke patients use higher MIVC% than control in Deltoid and Trapezius ms ( $p<0.05$ ).**
- 2. Stroke patients use all UE muscles relatively late than control ( $p<0.05$ ).**



A stack of papers is visible in the top-left corner, partially obscured by a blue banner. The banner contains the title text in white. The papers show some text, including 'Relative value' and percentages like '100%', '80%', '60%', and '40%'.

# Write indices correlation between sEMG indices during reaching

- 1. Muscular activation delay in reaching is correlated to slow pace of writing ( $0.568 < r < 0.911$ ,  $p < 0.05$ ).**
- 2. Efficient use of Deltoid muscle (i.e., MIVC% is low) during reaching is highly correlated in applying high writing pressure ( $0.636 < r < 0.8$ ).**



# Discussion and Conclusions

**Writing - Stroke patients are slower writers, put less pressure on the writing plate and spend more time in the air ('OFF') during the writing compared to healthy subjects.**

**'Reaching' in patients with stroke is characterized by inefficient activation of muscles (i.e., high MIVC%) , and a delay in activating muscles (delayed onset).**

**Treatment error augmentation is preferable than treating without error augmentation.**

# Thank you

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