

# The Lowest Vibration Spectra of High-Contrast Composite Structures

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# Outline

- Introduction
- Lowest-frequency vibrations of multi-component elastic structures
  - Rods
  - Antiplane motion of circular cylinders
  - Plates
- Concluding remarks

# 1. Introduction

#### High-contrast layered structures

• photovoltaic panels





• *laminated glass* 





www.dupont.com

www.gscglass.com

#### Sandwich structures

• Classical sandwich plate



• Foam insulation panels



# Introduction

### Soft robots

Rus & Tolley, 2015. Design, fabrication and control of soft robots. *Nature*, *521*(7553), 467. Stokes et al. A hybrid combining hard and soft robots. *Soft Robotics* 1.1 (2014): 70-74







# 2. Low-frequency vibrations of multi-component high-contrast elastic rods

J. Kaplunov et al., to appear

#### Contrast in

- Stiffness
- Density

• Length

 $\frac{E_i}{E_j}, \quad \frac{\rho_i}{\rho_j}, \quad \frac{l_i}{l_j}$ 

Small parameters  $\rightarrow$  asymptotic methods

#### Physical intuition:

Strong components (free ends) - almost rigid body motionsWeak components (fixed b.c.) - almost homogeneous deformations

## Toy problem: three-component rod (antisymmetric)

J. Kaplunov et al. J. Sound Vib. 366 (2016): 264-276

$$-h_1 - h_2$$
  $-h_1$   $O$   $h_1$   $h_1 + h_2$   $x$ 

Equations of motion

$$E_i \frac{d^2 u}{dx^2} + \rho_i \omega^2 u = 0, \qquad i = 1, 2.$$

Free ends

$$u'|_{\pm(h_1+h_2)}=0.$$

Continuity conditions

$$u|_{\pm(h_1+0)} = u|_{\pm(h_1-0)}, \qquad E_2 u|_{\pm(h_1+0)} = E_1 u|_{\pm(h_1-0)}.$$

# Frequency equation



Frequency equation

$$\tan \lambda_1 \tan \lambda_2 = \frac{E}{c}.$$

Low-frequency analysis in view of contrast:

- Global low-frequency behaviour  $(\lambda_i \ll 1, i = 1, 2)$
- Local low-frequency behaviour  $(\lambda_i \ll 1, \lambda_k \gtrsim 1, i \neq k)$

Global low-frequency behaviour

Conditions on material parameters

$$\lambda_1 \ll 1, \quad \lambda_2 \ll 1 \quad \Rightarrow$$
  
 $E \ll h \ll \rho^{-1}.$ 

Approximate frequency equation

$$\lambda_1 \lambda_2 = \frac{E}{c} \quad \Rightarrow \quad$$

$$\lambda_1 = \sqrt{E\rho}, \quad \lambda_2 = \sqrt{\frac{E}{h}}.$$

# Global low-frequency behaviour

Approximate polynomial eigenform

$$U = \begin{cases} 1, & |\chi| > 1; \\ \chi, & |\chi| \le 1. \end{cases}$$



# Local low-frequency behaviour

May occur for core or outer sections.

Approximate displacement profiles



 ${\mathcal E}$ 

Problem parameters

$$=\frac{E_2}{E_1} << 1, \qquad \rho_1 \sim \rho_2, \qquad L_i^j = \frac{l_j}{l_i}, \qquad c_m^2 = \frac{E_m}{\rho_m}.$$

 $l_1 \quad l_2$ 

Dimensionless scaling

$$X_{i} = \frac{x_{i}}{l_{i}}, \quad \Omega_{i} = \frac{\omega l_{i}}{c_{m}}, \quad b_{i} \le X_{i} \le b_{i} + 1, \quad b_{i} = l_{i}^{-1} \sum_{k=0}^{i-1} l_{k}, \quad i = \overline{1, n}; \quad m = 1, 2.$$

 $l_3$ 

 $l_5 \dots l_{n-2}$ 

 $l_4$ 

 $l_{n-1}$ 

 $l_n$ 

Equations of motion

Boundary conditions

Continuity

$$\frac{d^2 u_i}{dX_i^2} + \Omega_i^2 u_i = 0,$$

$$\begin{aligned} \frac{du_1}{dX_1}\Big|_{X_1=0} &= \frac{du_n}{dX_n}\Big|_{X_n=b_n+1} = 0, \\ u_i\Big|_{X_i=b_i+1} &= u_{i+1}\Big|_{X_{i+1}=b_{i+1}}, \quad \frac{du_i}{dX_i}\Big|_{X_i=b_i+1} = \varepsilon^j L_{i+1}^i \frac{du_{i+1}}{dX_{i+1}}\Big|_{X_{i+1}=b_{i+1}} \end{aligned}$$

 $(j=1 \text{ or } -1 \text{ for } i^{\text{th}} \text{ component being stiff or soft, respectively})$ 

Asymptotic expansions

$$u_i = u_{i0} + \mathcal{E}u_{i1} + \dots,$$

Global low-frequency regime

$$\Omega_i^2 \sim \varepsilon, \quad \Omega_i^2 = \varepsilon \Big( \Omega_{i0}^2 + \varepsilon \Omega_{i1}^2 + ... \Big).$$

• Leading order problem for stiff components

$$\frac{d^2 u_{i0}}{dX_i^2} = 0, \qquad \frac{du_{i0}}{dX_i} \bigg|_{X_i = b_i} = \frac{du_{i0}}{dX_i} \bigg|_{X_i = b_i + 1} = 0.$$

(almost rigid body motion)  $u_{i0} = C_i = \text{const}$ 





• Leading order problem for soft components

$$\frac{d^{2}u_{i0}}{dX_{i}^{2}} = 0, \qquad u_{i}\big|_{X_{i}=b_{i}} = C_{i-1}, \qquad u_{i}\big|_{X_{i}=b_{i}+1} = C_{i+1}.$$

$$u_{i0} = C_{i-1} + (C_{i+1} - C_{i-1})(X_{i} - b_{i}).$$

(almost homogeneous deformation)

From solvability of next order for stiff components

$$\Omega_{10}^{2} = L_{2}^{1} \left( 1 - \frac{C_{3}}{C_{1}} \right),$$

$$\vdots$$

$$\Omega_{i0}^{2} = \left( L_{i-1}^{i} - L_{i+1}^{i} \right) - L_{i-1}^{i} \frac{C_{i-2}}{C_{i}} - L_{i+1}^{i} \frac{C_{i+2}}{C_{i}},$$
Polynomial equation for frequency!
$$\vdots$$

$$\Omega_{n0}^{2} = L_{n-1}^{n} \left( 1 - \frac{C_{n-2}}{C_{n}} \right); \quad i = 1, 3, 5, ..., n.$$





### **Bicubic frequency equation**

$$\Omega_{10}^{6} + a_{1}\Omega_{10}^{4} + a_{2}\Omega_{10}^{2} = 0 \qquad \Longrightarrow \qquad \Omega_{10}^{2} = kL_{2}^{1}, \quad k = 0 \quad \text{or} \quad k = \frac{-a_{1} \pm \sqrt{a_{1}^{2} - 4a_{2}}}{2L_{2}^{1}}$$

### Approximate polynomial eigenform

 $u_{10} = 1,$   $u_{20} = 1 - k(X_2 - b_2),$   $u_{30} = 1 - k,$   $u_{40} = 1 - k + \frac{L_2^4 L_1^5 k(1 - k)}{1 - L_2^4 L_1^5 k} (X_4 - b_4),$  $u_{50} = \frac{1 - k}{1 - L_2^4 L_1^5 k}.$ 



#### Antiplane motion of concentric circular cylinders

Problem parameters

$$\varepsilon = \frac{\mu_1}{\mu_2} << 1, \quad \rho_1 \sim \rho_2, \quad L_i^j = \frac{l_j}{l_i}, \quad c_m^2 = \frac{\mu_m}{\rho_m}, \quad m = 1, 2.$$

 $R_i = \frac{r_i}{l_i}, \quad \Omega_i = \frac{\omega l_i}{c_m}, \quad b_i \le R_i \le b_i + 1, \quad b_i = l_i^{-1} \sum_{k=0}^{i-1} l_k, \quad i = \overline{1, n}.$ 

Equations of motion

$$R_i \frac{d^2 u_i}{dR_i^2} + \frac{du_i}{dR_i} + R_i \Omega_i^2 u_i = 0.$$

Boundary conditions

$$u_1\big|_{R_1=b_1} = u_n\big|_{R_n=b_n+1} = 0$$

Continuity

$$u_i|_{R_i=b_i+1} = u_{i+1}|_{R_{i+1}=b_{i+1}}, \quad \frac{du_i}{dR_i}|_{R_i=b_i+1} = \varepsilon^j L_{i+1}^i \frac{du_{i+1}}{dR_{i+1}}|_{R_{i+1}=b_{i+1}}.$$

 $(j = 1 \text{ or } -1 \text{ for } i^{\text{th}} \text{ component being stiff or soft, respectively})$ 



### Antiplane motion of concentric circular cylinders

Summary of the approach

• Global low-frequency perturbation

 Rigid body motions of stiffer components (at leading order)

• Leading order solution for softer components, involving logarithmic functions

• Solvability of the next order problem for stiffer components





### **Example:** Three-layered cylinder

Frequency

$$\Omega_{20}^2 = \frac{2\left(\delta_1 + \delta_3\right)}{2b_2 + 1}, \quad \delta_i = \frac{1}{\ln\left(1 + b_i^{-1}\right)}.$$



## Eigenform

$$u_{10} = \delta_1 \ln \left(\frac{R_1}{b_1}\right),$$
$$u_{20} = 1,$$
$$u_{30} = \delta_3 \ln \left(\frac{b_3 + 1}{R_3}\right)$$





#### Example: Five-layered cylinder



### Eigenform

 $\begin{aligned} u_{10} &= \delta_1 \ln \left(\frac{R_1}{b_1}\right), \\ u_{20} &= 1, \\ u_{30} &= -\delta_3 \left\{ \ln \left(\frac{R_3}{b_3 + 1}\right) - k \ln \left(\frac{R_3}{b_3}\right) \right\} \\ u_{40} &= k, \\ u_{50} &= k \delta_5 \ln \left(\frac{b_5 + 1}{R_5}\right). \end{aligned}$ 

Frequency 
$$\Omega_{20}^2 = \frac{2}{2b_2 + 1} (\delta_1 + (1 - k)\delta_3)$$
 (two roots for  $k$ )  
 $\left(\frac{R_3}{b_3}\right)$ ,  $\left(\frac{R_3}{$ 

## Low-frequency vibrations of high-contrast three-layered plates (antisymmetric)

# **Preliminary remarks**

• Rayleigh-Lamb dispersion relation for a single-layered plate

$$\gamma^4 \frac{\sinh \alpha}{\alpha} \cosh \beta - \beta^2 K^2 \cosh \alpha \frac{\sinh \beta}{\beta} = 0,$$

$$\alpha^{2} = K^{2} - \varkappa^{2} \Omega^{2}, \quad \beta^{2} = K^{2} - \Omega^{2}, \quad \gamma^{2} = K^{2} - \frac{1}{2} \Omega^{2}, \quad \varkappa = \frac{c_{2}}{c_{1}}$$
$$K = kh, \quad \Omega = \frac{\omega h}{c_{2}}$$



 $\label{eq:low-frequency} \begin{tabular}{l} $\Omega \ll 1$ \\ At the leading order $\Omega^2 \sim K^4$ \\ \end{tabular} \end{tabular} \end{tabular}$ 

 $\bigcirc$  High-frequency approximations near cut-off frequencies  $\Omega_* \sim 1$   $(|\Omega - \Omega_*| \ll 1)$ 

At the leading order  $K^2 \sim \Omega^2 - \Omega_*^2$ 

# Composite (non-uniformly asymptotic) plate theories

Originate from Timoshenko-Reissner-Mindlin ad hoc theories.



#### Contributions for composite plate and shells theories

V.L. Berdichevsky. Variational principles of continuum mechanics: I. Fundamentals. Springer Science and Business Media, 2009

K.C. Le. Vibrations of shells and rods. Springer Science and Business Media, 2012

I.V. Andrianov, J. Awrejcewicz, L.I. Manevitch. Asymptotical mechanics of thin-walled structures. Springer Science and Business Media, 2013

Low-frequency vibrations of high-contrast three-layered plates

Kaplunov et al. Int. J. Solids Struct. 113 (2017): 169-179

Statement of the problem

Equations of motion

 $\sigma_{ji,j} = \rho \ddot{u}_i, \quad i = 1,2$  for layers I and II

Boundary and continuity conditions

$$\sigma_{12}^{II} = 0, \quad \sigma_{22}^{II} = 0 \quad \text{at} \quad x_2 = h_1 + h_2$$
  
$$\sigma_{12}^{I} = \sigma_{12}^{II}, \quad \sigma_{22}^{I} = \sigma_{22}^{II} \quad \text{and} \quad u_1^{I} = u_1^{II}, \quad u_2^{I} = u_2^{II} \quad \text{at} \quad x_2 = h_1$$



# Dispersion relation

Ustinov, Doklady Physics (1976); Lee, Chang, Journal of Elasticity (1979)

$$\begin{aligned} 4K^{2}h^{3}\alpha_{2}\beta_{2}F_{4}\left[F_{1}F_{2}C_{\beta_{1}}S_{\alpha_{1}}-2\alpha_{1}\beta_{1}(\varepsilon-1)F_{3}C_{\alpha_{1}}S_{\beta_{1}}\right]+\\ h\alpha_{2}\beta_{2}C_{\alpha_{2}}C_{\beta_{2}}\left[4\alpha_{1}\beta_{1}K^{2}\left(h^{4}F_{3}^{2}+F_{4}^{2}(\varepsilon-1)^{2}\right)C_{\alpha_{1}}S_{\beta_{1}}-\\ \left(4K^{4}h^{4}F_{2}^{2}+F_{4}^{2}F_{1}^{2}\right)S_{\alpha_{1}}C_{\beta_{1}}\right]+\\ C_{\beta_{2}}S_{\alpha_{2}}\varepsilon\beta_{2}(\beta_{2}^{2}-K^{2}h^{2})(\beta_{1}^{2}-K^{2})\left[4\alpha_{2}^{2}\beta_{1}K^{2}h^{2}S_{\alpha_{1}}S_{\beta_{1}}-F_{4}^{2}\alpha_{1}C_{\alpha_{1}}C_{\beta_{1}}\right]+\\ C_{\alpha_{2}}S_{\beta_{2}}\varepsilon\alpha_{2}(\beta_{2}^{2}-K^{2}h^{2})(\beta_{1}^{2}-K^{2})\left[4\alpha_{1}\beta_{2}^{2}K^{2}h^{2}C_{\alpha_{1}}C_{\beta_{1}}-F_{4}^{2}\beta_{1}S_{\alpha_{1}}S_{\beta_{1}}\right]+\\ h^{3}S_{\alpha_{2}}S_{\beta_{2}}\left[\left(4\alpha_{2}^{2}\beta_{2}^{2}K^{2}F_{1}^{2}+K^{2}F_{4}^{2}F_{2}^{2}\right)C_{\beta_{1}}S_{\alpha_{1}}-\\ &\alpha_{1}\beta_{1}\left(16\alpha_{2}^{2}\beta_{2}^{2}(\varepsilon-1)^{2}K^{4}+F_{4}^{2}F_{3}^{2}\right)C_{\alpha_{1}}S_{\beta_{1}}\right]=0\end{aligned}$$

$$\begin{split} \Omega &= \frac{\omega h_1}{c_2^{\rm I}}, \quad K = kh_1, \qquad C_{\alpha_j}, C_{\beta_j}, S_{\alpha_j}, S_{\beta_j} \quad \text{- hyperbolic functions} \\ F_i, \quad i = 1..4, \qquad \alpha_j, \beta_j, \quad j = 1, 2 \quad \text{- functions of } \Omega \text{ and } K, \quad \varepsilon = \frac{\mu_1}{\mu_2} \end{split}$$

# Dispersion curves





# 1D eigenvalue problem for shear cut-off

Flexural motion  $\frac{\partial}{\partial x_1} = 0, \qquad u_2 = 0$ 

Frequency equation

$$\tan(\Omega)\tan\left(\sqrt{\frac{\varepsilon}{r}}h\ \Omega\right) = \sqrt{\varepsilon r}$$

Condition for a first shear cut-off frequency to be small

$$\label{eq:relation} \begin{split} r \ll h \ll \varepsilon^{-1} & \mbox{Frequency} \quad \Omega^2 \sim \end{split}$$
 where  $r = \frac{\rho_1}{\rho_2}, \quad h = \frac{h_2}{h_1}, \quad \varepsilon = \frac{\mu_1}{\mu_2}$ 



## Some three-layered structures satisfying the condition $r \ll h \ll \varepsilon^{-1}$

A) Photovoltaic panels  $\varepsilon \ll 1, h \sim 1, \rho \sim \varepsilon$ 

B) Laminated glass

 $\varepsilon \ll 1, \ h \sim \varepsilon^{-1/4}, \ \rho \sim 1$ 

C) Sandwich structure

$$\varepsilon \ll 1, \ h \sim \varepsilon, \ \rho \sim \varepsilon^2$$



(stiff skin layers and light core layer)

(stiff skin layers and light thin core layer)

(stiff thin skin layers and light core layer)

UNEXPECTEDLY LOW FIRST SHEAR CUT-OFF FREQUENCIES!

Long-wave low-frequency asymptotic approximation of the dispersion relation

For 
$$K \ll 1$$
 and  $\Omega \ll 1$   
 $\gamma_1 \Omega^2 + \gamma_2 K^4 + \gamma_3 K^2 \Omega^2 + \gamma_4 K^6 + \gamma_5 \Omega^4 + \gamma_6 K^4 \Omega^2 + \gamma_7 K^8 + \gamma_8 K^2 \Omega^4 + \gamma_9 K^2 \Omega^6 + \gamma_{10} \Omega^6 + ... = 0$ 

Multi-parametric analysis

$$\varepsilon \ll 1, \quad h \sim \varepsilon^{a}, \quad r \sim \varepsilon^{b}$$

Expanding coefficients

$$\gamma_i \to G_i \varepsilon^c$$

### Low-frequency dispersion behaviour

A) Photovoltaic panels  $\varepsilon \ll 1$ ,  $h \sim 1$ ,  $r \sim \varepsilon$  (stiff skin layers and light core layer )





Retain leading order terms for both: (i) fundamental mode ( $\Omega \sim K^2$ ) (ii) shear mode cut-off ( $\Omega_{sh} \sim \sqrt{\varepsilon}$ )

#### **UNIFORM TWO-MODE APPROXIMATIONS**

 $G_1 \varepsilon \Omega^2 + G_2 \varepsilon K^4 + G_3 K^2 \Omega^2 + G_4 K^6 + G_5 \Omega^4 = 0$ 

# Local approximations

Three local approximations



In the vicinity of zero frequency

$$G_1\Omega^2 + G_2K^4 = 0, \quad 0 < K \ll \sqrt{\varepsilon}, \quad \Omega \ll \varepsilon$$

At higher frequencies, including the vicinity of shear cut-off

 $G_3\Omega^2 + G_4K^4 = 0, \quad \sqrt{\varepsilon} \ll K \ll 1, \quad \varepsilon \ll \Omega \ll 1$ 



CLASSICAL KIRCHHOFF-TYPE THEORY IS NOT APPLICABLE!

Uniform approximation for the fundamental mode

Taking both local approximations we derive a uniform one:

 $G_1 \varepsilon \Omega^2 + G_2 \varepsilon K^4 + G_3 K^2 \Omega^2 + G_4 K^6 = 0$ 



Also valid in the transition region  $\Omega \sim \varepsilon, K \sim \sqrt{\varepsilon}$ 

# Near shear cut-off approximation

For  $\Omega \sim \sqrt{\varepsilon}$ ,  $K \ll 1$  $G_1 \varepsilon + G_3 K^2 + G_5 \Omega^2 = 0$ 



### Low-frequency dispersion behaviour

J. Kaplunov et al. *Proc. Eng.* 199 (2017): 1489-1494

B) Laminated glass (stiff skin layers and light light core layer)

$$\varepsilon \ll 1, \ h \sim \varepsilon^{-1/4}, \ \rho \sim 1$$





#### **UNIFORM TWO-MODE APPROXIMATIONS**

$$\varepsilon^{11/4}G_1\Omega^2 + \varepsilon^{5/4}G_2K^4 + \varepsilon^{3/2}G_3K^2\Omega^2 + G_4K^6 + \varepsilon^{5/2}G_5\Omega^4 = 0$$

### Low-frequency dispersion behaviour

C) Sandwich structure  $\varepsilon \ll 1$ ,  $h \sim \varepsilon$ ,  $r \sim \varepsilon^2$  (stiff thin skin layers and light core layer )





**COMPOSITE APPROXIMATIONS** 

 $G_1 \varepsilon \Omega^2 + G_2 \varepsilon^2 K^4$ 

$$+\varepsilon K^2 \Omega^2 \left(G_3 + \frac{r_0}{h_0}G_8\right) + G_5 \Omega^4 = 0$$



## In progress

• Asymptotic models for strongly inhomogeneous plates



uniformly asymptotic

$$G_1 \varepsilon u_{tt} + G_2 \varepsilon \Delta^2 u + G_3 \Delta u_{tt}$$
$$- G_4 \Delta^3 u + G_5 u_{tttt} = 0$$

composite

 $G_1 \varepsilon u_{tt} + G_2 \varepsilon^2 \Delta^2 u + G_5 u_{tttt}$  $+ \varepsilon \left( G_3 + \frac{r_0}{h_0} G_8 \right) \Delta u_{tt} = 0$ 

- Boundary conditions
- Extension to layered shells

# **Concluding remarks**

- ✓ Multi-component high-contrast elastic structures require specialised theory
- ✓ High contrast may lead to unexpectedly low natural frequencies
- ✓ Stronger components subject to Neumann conditions, perform almost rigid body motions
- ✓ Two-mode theories for long-wave low-frequency motion of layered plates can be asymptotically uniform or composite