Title: Analysis and simulation of aerial unmanned vehicle using pure pursuit guidance law.

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Abstract: In th is paper an analysis and simulation of aerial unmanned vehicle is presented The three degree of freedom [3DOF] equations of motion for the aerial unmanned vehicle is proofed using pure pursuit guidance method which is known as path planning algorithm. The pure pursuit guidanee method was stretched well beyond its intended usage by many aerospace applicat ions. The pure pursuil algorithm is used to accomplish goal-seeking and path tracking. An analysis and flight trajectory simulalion for the aerial unmanned vehicle is given based on MATLAB program

Biography:

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